

1 P-instructions

1.1 Expressions and Assignments

instruction	meaning	condition	result	comments	references
add N	STORE[SP - 1] := STORE[SP - 1] + _N STORE[SP]; SP := SP - 1	(N, N)	(N)		tab. 2.1, p. 11
sub N	STORE[SP - 1] := STORE[SP - 1] - _N STORE[SP]; SP := SP - 1	(N, N)	(N)		tab. 2.1, p. 11
mul N	STORE[SP - 1] := STORE[SP - 1] * _N STORE[SP]; SP := SP - 1	(N, N)	(N)		tab. 2.1, p. 11
div N	STORE[SP - 1] := STORE[SP - 1] / _N STORE[SP]; SP := SP - 1	(N, N)	(N)		tab. 2.1, p. 11
neg N	STORE[SP] := - _N STORE[SP];	(N)	(N)		tab. 2.1, p. 11
and	STORE[SP - 1] := STORE[SP - 1] and STORE[SP]; SP := SP - 1	(b, b)	(b)		tab. 2.1, p. 11
or	STORE[SP - 1] := STORE[SP - 1] or STORE[SP]; SP := SP - 1	(b, b)	(b)		tab. 2.1, p. 11
not	STORE[SP] := note STORE[SP];	(b)	(b)		tab. 2.1, p. 11
equ T	STORE[SP - 1] := STORE[SP - 1] = _T STORE[SP]; SP := SP - 1	(T, T)	(b)		tab. 2.1, p. 11
geq T	STORE[SP - 1] := STORE[SP - 1] ≥ _T STORE[SP]; SP := SP - 1	(T, T)	(b)		tab. 2.1, p. 11
leq T	STORE[SP - 1] := STORE[SP - 1] ≤ _T STORE[SP]; SP := SP - 1	(T, T)	(b)		tab. 2.1, p. 11
les T	STORE[SP - 1] := STORE[SP - 1] < _T STORE[SP]; SP := SP - 1	(T, T)	(b)		tab. 2.1, p. 11
grt T	STORE[SP - 1] := STORE[SP - 1] > _T STORE[SP]; SP := SP - 1	(T, T)	(b)		tab. 2.1, p. 11

instruction	meaning	condition	result	comments	references
neq T	STORE[SP - 1] := STORE[SP - 1] ≠ _T STORE[SP]; SP := SP - 1	(T, T)	(b)		tab. 2.1, p. 11

1.2 Store and Load Instructions

instruction	meaning	condition	result	comments	references
ldo T q	SP := SP + 1; STORE[SP] := STORE[Q]	$q \in [0, \text{maxstr}]$	(T)	load location given by absolute address on top of stack	tab. 2.2, p. 12
ldc T q	SP := SP + 1; STORE[SP] := q	type(q) = T	(T)	load constant q on top of stack	tab. 2.2, p. 12
ind T	STORE[SP] := STORE[STORE[SP]]	(a)	(T)	load indirectly using highest stack location	tab. 2.2, p. 12
sro T q	STORE[q] := STORE[SP]; SP := SP - 1	(T) $q \in [0, \text{maxstr}]$		stores in location addressed by absolute address	tab. 2.2, p. 12
sto T	STORE[STORE[SP - 1]] := STORE[SP]; SP := SP - 2	(a, T)		stores in location addressed by 2 nd highest stack location	tab. 2.2, p. 12

1.3 Conditional and Iterative Statements

instruction	meaning	condition	result	comments	references
ujp q	PC := q	$q \in [0, \text{codemax}]$		unconditional branch	tab. 2.4, p. 14
fjp q	if STORE[SP] = false then PC := q fi SP := SP - 1	(b) $q \in [0, \text{codemax}]$		conditional branch	tab. 2.4, p. 14

instruction	meaning	condition	result	comments	references
ixj q	PC := STORE[SP] + q; SP := SP - 1		(i)	indexed branch (switch)	tab. 2.5, p. 17
ixa q	STORE[SP - 1] := STORE[SP - 1] + STORE[SP] * q; SP := SP - 1	(a, i)	(a)	indexed address computation: start address in STORE[SP - 1], index of selected subarray in STORE[SP], $q = g \cdot d^{(j)}$ subarray size	tab. 2.6, p. 22
inc T	STORE[SP] := STORE[SP] + q	(T) and type(q) = i	(T)		tab. 2.7, p. 23
dec T	STORE[SP] := STORE[SP] - q	(T) and type(q) = i	(T)		tab. 2.7, p. 23

1.4 Array Indexation

instruction	meaning	condition	result	comments	references
chk $p\ q$	if (STORE[SP] < p) or (STORE[SP] > q) then error('value out of range') fi	(i,i)	(i)	check array boundaries	tab. 2.8, p. 23
dpl T	$SP := SP + 1;$ STORE[SP] := STORE[SP - 1]	(T)	(T,T)	copies highest stack entry	tab. 2.9, p. 27 tab. 2.9, p. 27
ldd T	$SP := SP + 1;$ STORE[SP] := STORE[STORE[SP - 3] + q]	(a, T_1, T_2)	(a, T_1, T_2, i)	indirect access to descriptor arrays	tab. 2.9, p. 27 tab. 2.9, p. 27
sli T_2	STORE[SP - 1] := STORE[SP]; $SP := SP - 1$	(T_1, T_2)	(T_2)	move highest stack entry in 2 nd highest position	tab. 2.9, p. 27

1.5 Dynamic Memory Allocation

instruction	meaning	condition	result	comments	references
new	if NP - STORE[SP] ≤ EP then error('store overflow') else NP := NP - STORE[SP]; STORE[STORE[SP - 1]] := NP; SP := SP - 2; fi	(a, i)		object size at top of stack address of pointer just below ptr → object start address	tab. 2.10, p. 29 fig. 2.7, p. 30

1.6 Procedure Calls and Frames on the Stack

1.6.1 Loading and Storing Bound and Free Variables

instruction	meaning	condition	result	comments	references
lod $T\ p\ q$	$SP := SP + 1;$ STORE[SP] := STORE[base(p, MP) + q]		(T)	load a value of type T nesting depth p , relative address q	tab. 2.11, p. 42
lda $p\ q$	$SP := SP + 1;$ STORE[SP] := base(p, MP) + q		(a)	loads addresses nesting depth p , relative address q	tab. 2.11, p. 42
str $T\ p\ q$	STORE[base(p, MP) + q] := STORE[SP]; $SP := SP - 1$		(T)	storing values nesting depth p , relative address q	tab. 2.11, p. 42
!!!	base(p, a) = if $p = 0$ then a else base($p - 1$, STORE[a + 1]) fi: e.g. base(d, MP) follows SL chain d times to return MP of the predecessor frame (Fig. 2.12, p. 42)				!!!

1.6.2 Instructions for Calling and Entering Procedures (Caller)

instruction	meaning	condition	result	comments	references
mst p	STORE[SP + 2] := base(p, MP); STORE[SP + 3] := MP; STORE[SP + 4] := EP; $SP := SP + 5$;		stack marked with organisational block	set SL to point to static predecessor's MP p nrof times to follow SL-chain set DL to point to start of caller's frame save EP location for return address reserved; params can now be evaluated from STORE[SP + 1]	tab. 2.12, p. 47 Fig. 2.12, p. 42 Fig. 2.11, p. 40
cup $p\ q$	MP := SP - (p + 4); STORE[MP + 4] := PC; PC := q;		call user procedure	p: params storage requirement save return address proc. init. routine start address q in CODE	tab. 2.12, p. 47
!!!	base(p, a) = if $p = 0$ then a else base($p - 1$, STORE[a + 1]) fi: e.g. base(d, MP) follows SL chain d times (Fig. 2.12, p. 42)				!!!

1.6.3 Instructions for Returning

instruction	meaning	condition	result	comments	references
retf	$SP := MP;$ PC := STORE[MP + 4]; EP := STORE[MP + 3]; if $EP \geq NP$ then error('store overflow') fi MP := STORE[MP + 2]		leaves result at top of stack	function result in local stack return branch restore EP release current stack frame revert via DL ptr	tab. 2.13, p. 48
retp	$SP := MP - 1;$ PC := STORE[MP + 4]; EP := STORE[MP + 3]; if $EP \geq NP$ then error('store overflow') fi MP := STORE[MP + 2]			procedure w/o results return branch restore EP release current stack frame revert via DL ptr	tab. 2.13, p. 48

1.6.4 Instructions for Calling and Entering Procedures (Callee)

instruction	meaning	condition	result	comments	references
ssp <i>p</i>	$SP := MP + p - 1$			set stack pointer <i>p</i> size of static part data area	tab. 2.12, p. 47
sep <i>p</i>	$EP := SP + p;$ if $EP \geq NP$ then error('store overflow') fi ;			set extreme pointer <i>p</i> max. depth of local stack collision check stack, heap	tab. 2.12, p. 47
!!!	$base(p, a) = \text{if } p = 0 \text{ then } a \text{ else } base(p - 1, STORE[a + 1]) \text{ fi}$: e.g. $base(d, MP)$ follows SL chain <i>d</i> times (Fig. 2.12, p. 42)				!!!

1.6.5 Block Copy Instructions

instruction	meaning	condition	result	comments	references
movs <i>q</i>	for $i := q - 1$ down to 0 do $STORE[SP + i] := STORE[STORE[SP] + i]$ od ; $SP := SP + q - 1$	(a)		$STORE[SP]$ holds begin addresss structured type (backward copying; begin address TOS overwritten)	tab. 2.14, p. 50
movd <i>q</i>	for $i := 1$ to $STORE[MP + q + 1]$ do $STORE[SP + i] := STORE[STORE[MP + q] + STORE[MP + q + 2] + i - 1]$ od ; $SP := SP + STORE[MP + q + 1]$				tab. 2.14, p. 50

2 Generating P-code Instruction Sequences: Compilation Schemes

2.1 Schemata for Expression Evaluation, Assignment and Statement Sequences

	Function	$(\rho : Var \mapsto \mathbb{N}_0; \text{maps variable to relative address})$	Condition	References
1	$code_R(e_1 = e_2) \rho$	$= code_R e_1 \rho; code_R e_2 \rho; \text{equ } T$	$\text{type}(e_1) = \text{type}(e_2) = T$	p. 13
2	$code_R(e_1 \neq e_2) \rho$	$= code_R e_1 \rho; code_R e_2 \rho; \text{neq } T$	$\text{type}(e_1) = \text{type}(e_2) = T$	p. 13
*				tab. 2.1, p. 11
3	$code_R(e_1 + e_2) \rho$	$= code_R e_1 \rho; code_R e_2 \rho; \text{add } N$	$\text{type}(e_1) = \text{type}(e_2) = N$	p. 13
4	$code_R(e_1 - e_2) \rho$	$= code_R e_1 \rho; code_R e_2 \rho; \text{sub } N$	$\text{type}(e_1) = \text{type}(e_2) = N$	p. 13
5	$code_R(e_1 * e_2) \rho$	$= code_R e_1 \rho; code_R e_2 \rho; \text{mul } N$	$\text{type}(e_1) = \text{type}(e_2) = N$	p. 13
6	$code_R(e_1 / e_2) \rho$	$= code_R e_1 \rho; code_R e_2 \rho; \text{div } N$	$\text{type}(e_1) = \text{type}(e_2) = N$	p. 13
7	$code_R(-e) \rho$	$= code_R e \rho; \text{neg } N$	$\text{type}(e) = N$	p. 13
8	$code_R(x := e) \rho$	$= code_L x \rho; \text{ind } T$	x variable identifier of type T	p. 13
9	$code_R(c) \rho$	$= ldc T c$	c constant of type T	p. 13
10	$code(x := e) \rho$	$= code_L x \rho; code_R e \rho; \text{sto } T$	x variable identifier	p. 13
11	$code_L x \rho$	$= ldc a \rho(x)$	x variable identifier	p. 13
12	$code(\text{if } e \text{ then } st_1 \text{ else } st_2 \text{ fi}) \rho$	$= code_R e \rho; \text{fjp } l_1; code st_1 \rho; \text{ujp } l_2; l_1:code st_2 \rho; l_2:$	e boolean expression	p. 14
13	$code(\text{if } e \text{ then } st \text{ fi}) \rho$	$= code_R e \rho; \text{fjp } l; code st \rho; l:$	e boolean expression	p. 14
14	$code(\text{while } e \text{ do } st \text{ od}) \rho$	$= l_1:code_R e \rho; \text{fjp } l_2; code st \rho; \text{ujp } l_1; l_2:$	e boolean expression	p. 14
15	$code(\text{repeat } st \text{ until } e) \rho$	$= l:code st \rho; code_R e \rho; \text{fjp } l$	e boolean expression	p. 14
16	$code(st_1; st_2) \rho$	$= code st_1 \rho; code st_2 \rho$		p. 15

2.2 Array-Related Schemata

	Function $(\rho : Var \mapsto \mathbb{N}_0; \text{maps variable to relative address})$	Condition	References
17	$code_L c[i_1, \dots, i_k] \rho = \mathbf{ldc} a \rho(c); code_I [i_1, \dots, i_k] g \rho$	array components of type T ; $g = \text{size}(T)$ $\text{type}(i_1) = \dots = \text{type}(i_k) = N$	p. 23
18a	$code_I [i_1, \dots, i_k] g \rho = code_R i_1 \rho; \mathbf{ixa} g \cdot d^{(1)};$ $code_R i_2 \rho; \mathbf{ixa} g \cdot d^{(2)};$ \vdots $code_R i_k \rho; \mathbf{ixa} g \cdot d^{(k)};$ $\mathbf{dec} a g \cdot d$	array components of type T ; $g = \text{size}(T)$ $\text{type}(i_1) = \dots = \text{type}(i_k) = N$ $d = \sum_{j=1}^k u_j \cdot d^{(j)}$; $d^{(j)} = \prod_{l=j+1}^k d_l$ d_l ranges of array dimensions	pp. 22–23
18b	$code_I [i_1, \dots, i_k] arr \rho = code_R i_1 \rho; \mathbf{chk} u_1 o_1; \mathbf{ixa} g \cdot d^{(1)};$ $code_R i_2 \rho; \mathbf{chk} u_2 o_2; \mathbf{ixa} g \cdot d^{(2)};$ \vdots $code_R i_k \rho; \mathbf{chk} u_k o_k; \mathbf{ixa} g \cdot d^{(k)};$ $\mathbf{dec} a g \cdot d$	array components of type T ; $g = \text{size}(T)$ $\text{type}(i_1) = \dots = \text{type}(i_k) = N$ $d = \sum_{j=1}^k u_j \cdot d^{(j)}$; $d^{(j)} = \prod_{l=j+1}^k d_l$ d_l ranges of array dimensions $arr = (g; u_1, o_1, \dots, u_k, o_k)$	pp. 22–23
19	$code_{Ld} b[i_1, \dots, i_k] \rho = \mathbf{ldc} a \rho(b);$ $code_{Id} [i_1, \dots, i_k] g \rho$	load descriptor address (static) component size g	p. 26
20	$code_{Id} [i_1, \dots, i_k] g \rho = \mathbf{dpl} i;$ $\mathbf{ind} i;$ $\mathbf{ldc} i 0;$ $code_R i_1 \rho; \mathbf{add} i; \mathbf{ldd} 2k + 3; \mathbf{mul} i;$ $code_R i_2 \rho; \mathbf{add} i; \mathbf{ldd} 2k + 4; \mathbf{mul} i;$ \vdots $code_R i_{k-1} \rho; \mathbf{add} i; \mathbf{ldd} 3k + 1; \mathbf{mul} i;$ $code_R i_k \rho; \mathbf{add} i;$ $\mathbf{ixa} g;$ $\mathbf{sli} a;$	duplicate highest stack entry (descriptor address) load fictitious start address via upper duplicate Horner scheme; retrieve and account for d_2 Horner scheme; retrieve and account for d_3 Horner scheme; retrieve and account for d_{k-1} Horner scheme; account for last term indexed address: add offset to fictitious address pop redundant address value (2^{nd} highest stack entry)	p. 26 p. 25 p. 25 p. 25 p. 25 p. 25 p. 25

2.3 Record- and Pointer-Related Schemata

	Function $(\rho : Var \mapsto \mathbb{N}_0; \text{maps variable to relative address})$	Condition	References
21	$code_L c_i v \rho = \mathbf{ldc} a \rho(v); \mathbf{inc} a \rho(c_i)$	$\text{type}(c_i) = T$; c_i component in record v ; $\rho(c_i) = \sum_{j=1}^{i-1} \text{size}(t_j)$ for sizes	p. 28
22	$code(\mathbf{new}(x)) \rho = \mathbf{ldc} a \rho(x); \mathbf{ldc} i \text{size}(t); \mathbf{new}$	if x is a variable of type $\uparrow t$ cf. P-instruction new for upper 2 stack entries	p. 30
23	$code_L(xr) \rho = \mathbf{ldc} a \rho(x); code_M(r) \rho$	for name x (variable reference)	p. 31
24	$code_M(.xr) \rho = \mathbf{inc} a \rho(x); code_M(r) \rho$	for name x (record field section)	p. 31
25	$code_M(\uparrow r) \rho = \mathbf{ind} a; code_M(r) \rho$	(pointer dereferencing)	p. 31
26	$code_M([i]r) \rho = code_{I(d)} [i] g \rho; code_M(r) \rho$	component size g of array (array indexing)	p. 31
27	$code_M(\epsilon) = \epsilon$	(empty statement)	p. 31

2.4 Schemata for Procedure and Function Calls

	Function	Condition	References
29	$code\ p(e_1, \dots, e_k)\ \rho\ st = \mathbf{mst}\ st - st';$ $\quad code_A\ e_1\ \rho\ st;$ $\quad \vdots$ $\quad code_A\ e_k\ \rho\ st;$ $\quad \mathbf{cup}\ s\ l;$	$st =$ nesting depth procedure call $st' =$ nesting depth procedure declaration $\rho(p) = (l, st')$ $s =$ storage requirements actual params $l =$ CODE address of ssp instr. rule 28/30	p. 49 steps p. 46
28	$code\ (\mathbf{proc}\ p(specs);\ vdecls;\ pdecls;\ body)\ \rho\ st =$ $\quad \mathbf{ssp}\ n_a'';$ $\quad code_P\ specs\ \rho'\ st;$ $\quad code_P\ vdecls\ \rho''\ st;$ $\quad \mathbf{sep}\ k;$ $\quad \mathbf{ujp}\ l;$ $\quad proc_code;$ $\quad l : code\ body\ \rho'''\ st;$ $\quad \mathbf{ret}[f p]$	$st =$ nesting depth procedure declaration storage requirements static part storage requirements dynamic part create and initialise variables k max. depth local stack l = procedure start CODE address code for local procedures code for procedure body $(\rho', n_a') = elab_specs\ specs\ \rho\ 5\ st$ $(\rho'', n_a'') = elab_vdecls\ vdecls\ \rho'\ n_a'\ st$ $(\rho''', proc_code) = elab_pdecls\ pdecls\ \rho''\ st$	p. 49 steps p. 46
30	$code\ (\mathbf{program}\ vdecls;\ pdecls;\ stats)\ \rho_0 =$ $\quad \mathbf{ssp}\ n_a;$ $\quad code_P\ vdecls\ \rho\ 1;$ $\quad \mathbf{sep}\ k;$ $\quad \mathbf{ujp}\ l;$ $\quad proc_code;$ $\quad l : code\ stats\ \rho'\ st;$ $\quad \mathbf{stp}$	$\rho_0:$ all registers initialised to 0; SP to -1 SP after organisational block generate code to fill array descriptors k max. depth local stack l = procedure start CODE address code for local procedures $st = 1$ nesting depth stop P-machine $(\rho, n_a) = elab_vdecls\ vdecls\ \rho_0\ 5\ 1$ $(\rho', proc_code) = elab_pdecls\ pdecls\ \rho\ 1$	p. 56 steps p. 46
37	$code\ (\mathbf{return}\ [e x])\ \rho\ st = code_R\ [e x]\ \rho\ st;$ $\quad \mathbf{str}\ T\ 0\ 0;$	T is type of expression e or variable/parameter x	

2.5 Schemata for Parameter Passing

	Function	Condition	References
31	$code_A\ x\ \rho\ st = code_L\ x\ \rho\ st;$	parameter corresponding to x is var/reference parameter	p. 49
32	$code_A\ e\ \rho\ st = code_R\ e\ \rho\ st;$	parameter corresponding to e is value parameter of scalar type	p. 50
33	$code_A\ x\ \rho\ st = code_L\ x\ \rho\ st;$ $\quad \mathbf{movs}\ s;$	parameter corresponding to e is of structured type t (record, descriptor) with static $size(t) = s$	p. 50
34	$code_P(\mathbf{value}\ x : \mathbf{array}[u_1..o_1, \dots, u_k..o_k] \mathbf{of}\ t)\ \rho\ st = movd\ ra$	copy the array	p. 52

2.6 Schemata for Access to Variables and Formal Parameters

	Function	Condition	References
35	$code_L(x\ r)\ \rho\ st = \mathbf{lda}\ d\ ra;$ $\quad code_M\ r\ \rho\ st$	$\rho(x) = (ra, st')$, $d = st - st'$ is difference in nesting depths of applied and defining occurrences local variable or formal value parameter x	p. 53 steps p. 46
36	$code_L(x\ r)\ \rho\ st = \mathbf{lod}\ a\ d\ ra;$ $\quad code_M\ r\ \rho\ st$	$\rho(x) = (ra, st')$, $d = st - st'$ is difference in nesting depths of applied and defining occurrences formal var parameter x (by reference)	p. 53 steps p. 46

!!! r is a word describing indexing, selection or dereferencing: cf. 23 – 27 !!!